



- 1

- 2

G_0

G

m

$t = 0 \text{ s}$

:
 \vec{v}_0

α

- 1 - 1

G

m

()

$$\left(\vec{0}, \vec{i}, \vec{j}, \vec{k} \right)$$

\vec{V}_0

G_0

$t = 0$

$t = 0 \text{ s}$

\vec{V}_0

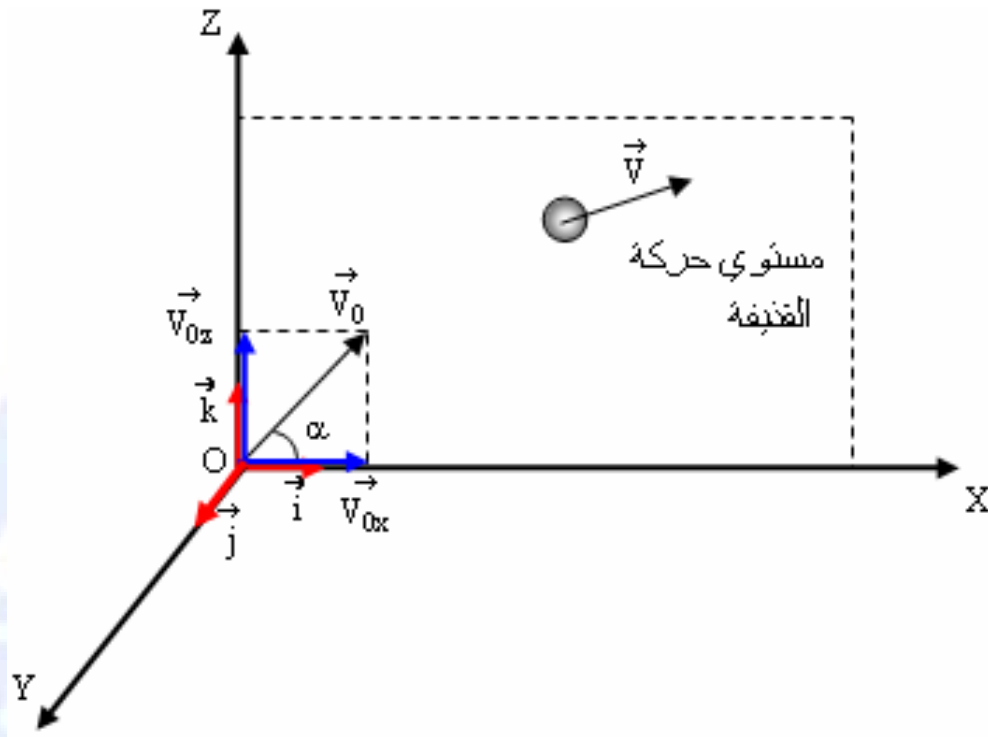
G_0

G

$t = 0 \text{ s}$

$$\vec{OG}(t = 0) = \vec{OG}_0 = 0 \vec{i} + 0 \vec{j} + 0 \vec{k}$$

$$\vec{v}(t = 0) = \vec{v}_0 = v_{0x} \vec{i} + 0 \vec{j} + v_{0z} \vec{k}$$



$$\vec{v}_0 = v_0 \cos \alpha \cdot \vec{i} + 0 \cdot \vec{j} + v_0 \sin \alpha \cdot \vec{k}$$

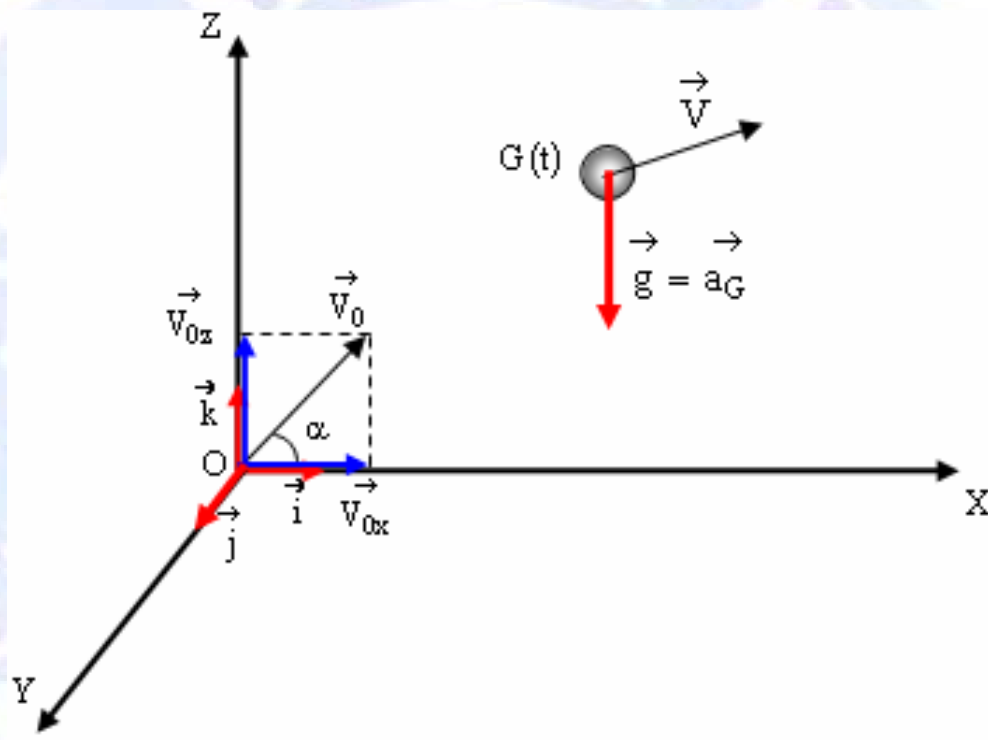
$$\vec{P} = m \cdot \vec{g}$$

$$\vec{F}_A$$

$$\vec{F}_f$$

$$\vec{P} = m \cdot \vec{g}$$

$$\sum \vec{F} = m \cdot \vec{a}_G :$$



$$m \cdot \vec{g} = m \cdot \vec{a}_G$$

$$\vec{g} = \vec{a}_G$$

$$\left(\begin{array}{ccc} \vec{0}, \vec{i}, \vec{j}, \vec{k} \end{array} \right)$$

$$: \vec{a}_G$$

$$a_x = 0 :$$

$$\vec{a}_x = 0$$

$$a_y = 0 :$$

$$\vec{a}_y = 0$$

$$a_z = -g :$$

$$\vec{a}_z = g$$

$$\boxed{\frac{dv_z}{dt} = -g}$$

$$\boxed{\frac{dv_y}{dt} = 0}$$

$$\boxed{\frac{dv_x}{dt} = 0}$$

: - 2 - 1 /

$$: \left(\begin{array}{ccc} \vec{0}, \vec{i}, \vec{j}, \vec{k} \end{array} \right)$$

$$\vec{v} \left(\begin{array}{ccc} \vec{v}_x, \vec{v}_y, \vec{v}_z \end{array} \right)$$

$$\vec{v} = v_x \cdot \vec{i} + v_y \cdot \vec{j} + v_z \cdot \vec{k}$$

$$v = \sqrt{v_x^2 + v_y^2 + v_z^2}$$

t

\vec{OX} -

$$\frac{dv_x}{dt} = 0$$

$$v_x = C_1$$

C_1

\vec{OY} -

$$\frac{dv_y}{dt} = 0$$

$$v_y = C_2$$

C_2

\vec{OZ} -

$$dv_y = -gdt :$$

$$\frac{dv_y}{dt} = -g :$$

$$\int dv_y = -\int gdt :$$

$$v_y = -gt + C_3$$

C_3

$$v_z = -gt + C_3 \quad v_y = C_2 \quad v_x = C_1$$

$$\vec{v}(t=0) = \vec{v}_0 = v_{0x} \vec{i} + 0 \vec{j} + v_{0z} \vec{k}$$

$$C_3 = v_{0z} \quad C_2 = v_{0y} = 0 \quad C_1 = v_{0x}$$

$$\left(\vec{0}, \vec{i}, \vec{j}, \vec{k} \right)$$

$$\vec{v} = (v_{0x}) \vec{i} + 0 \vec{j} (-gt + v_{0y}) \vec{k}$$

:G

$$\left(\vec{0}, \vec{i}, \vec{j}, \vec{k} \right)$$

(x, y, z)

$$\vec{OG} = x(t) \vec{i} + y(t) \vec{j} + z(t) \vec{k}$$

: x(t)

$$.dx = v_{0x} dt : \quad v_x = v_{0x} = \frac{dx}{dt} :$$

$$: \int dx = v_{0x} \int dt :$$

$$x = v_{0x} t + k_1$$

: x(t)

$$.dy = 0 dt : \quad v_y = v_{0y} = \frac{dy}{dt} = 0 :$$

$$y = k_1$$

: z(t)

$$dz = v_z dt = (-gt + v_{0z}) dt \quad : \quad v_z = \frac{dz}{dt}$$

$$: \int dz = -g \int t dt + v_{0z} \int dt :$$

$$z = -\frac{1}{2}gt^2 + v_{0z}t + k_3$$

$$: \quad \vec{OG}(t=0) = \vec{OG}_0 = 0 \overset{k_3}{\vec{i}} + 0 \overset{k_2}{\vec{j}} + 0 \overset{k_1}{\vec{k}}$$

$$: \quad \left(\overset{k_3=0}{0}, \overset{k_2=0}{\vec{i}}, \overset{k_1=0}{\vec{j}, \vec{k}} \right)$$

$$\vec{OG} = (v_0 \cos \alpha t) \vec{i} + 0 \vec{j} + \left(-\frac{1}{2}gt^2 + v_0 \sin \alpha t \right) \vec{k}$$

- 3 - 1

$$\left(\overset{\rightarrow}{0}, \vec{i}, \vec{j}, \vec{k} \right)$$

$$. z = f(x) \quad \vec{OZ} \quad \vec{OX}$$

$$\begin{cases} x = v_0 \cos \alpha t \dots\dots\dots(1) \\ y = 0 \\ z = -\frac{1}{2}gt^2 + v_0 \sin \alpha t \dots\dots\dots(2) \end{cases}$$

:(2)

(1)

: (1)

$$t = \frac{x}{v_0 \cos \alpha} \dots\dots\dots(3)$$

: (2) (3)

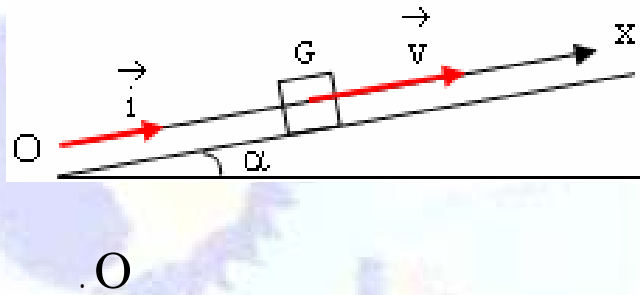
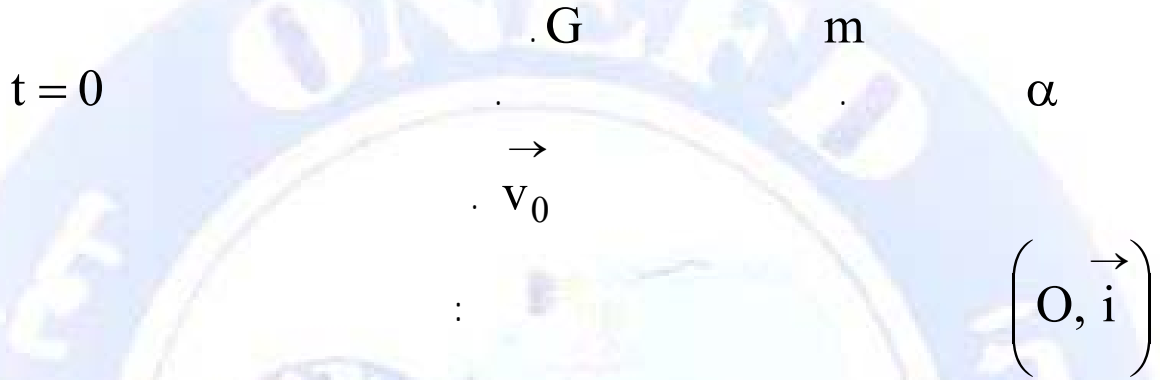
$$z = -\frac{g}{2 v_0^2 \cos^2 \alpha} x^2 + \operatorname{tg} \alpha x$$

$$z = ax^2 + bx :$$

$$\rightarrow v_0$$

$$\rightarrow OG_0$$

x



$v = f(t)$ - 1

$x = f(t)$ - 2

M - 3

M

$v_0 \sin \alpha \quad g \quad x_M$ - 4

$v_0 \quad \alpha = 10^\circ$ - 5

$x_M = 80\text{cm} \quad M$ - 6

- 1

- 2

- 3

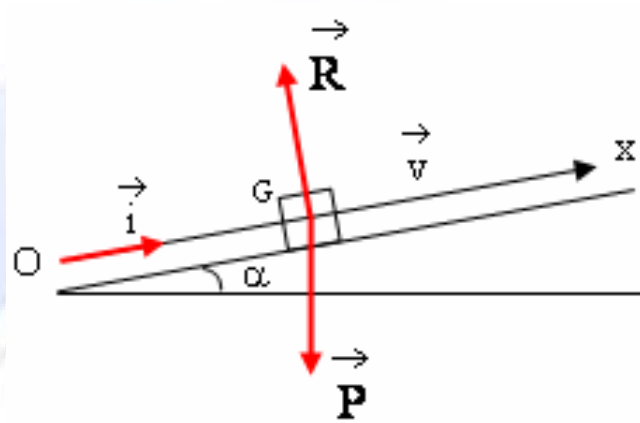
- 4

- 5

- 6

- 7

:
- 1



- 2

$$\vec{P} + \vec{R} = m \vec{a}$$

: $\left(O, \vec{i} \right)$

$$m a = -m g \sin \alpha$$

$$\boxed{\frac{dv}{dt} = -g \sin \alpha}$$

$$\frac{dv}{dt} = \text{cst}$$

$$v = f(t)$$

- 3

$$v = -g \sin \alpha t + C_1 \quad ; \quad dv = -g \sin \alpha dt$$

C_1

$$\vec{v}_0 = v_{0x} \vec{i} + 0 \vec{j} + 0 \vec{k} \quad ; \quad t = 0$$

$$v(t=0) = -g \sin \alpha \times 0 + C_1 = v_0$$

:

$$v(t) = -g \sin \alpha t + v_0$$

:

:

$$\vec{v}(t) = (-g \sin \alpha t + v_0) \vec{i} + 0 \vec{j} + 0 \vec{k}$$

$$x = f(t)$$

- 4

$$: \quad dx = v dt = (-g \sin \alpha t + v_0) dt :$$

$$x = -\frac{1}{2} g \sin \alpha t^2 + v_0 t + C_2$$

:

C_2

$$x(t=0) = x_0 = -\frac{1}{2} g \sin \alpha \times 0^2 + v_0 \times 0 + C_2 = 0$$

:

$$x(t) = -\frac{1}{2} g \sin \alpha t^2 + v_0 t$$

:

:

$$\vec{OG}(t) = \left(-\frac{1}{2} g \sin \alpha t^2 + v_0 t \right) \vec{i} + 0 \vec{j} + 0 \vec{k}$$

:

M

- 5

$$v(M) = -g \sin \alpha t + v_0 = 0$$

$$t = \frac{v_0}{g \sin \alpha}$$

$$: \quad t = \frac{v_0}{g \sin \alpha} \quad - 6$$

$$x_M = \frac{v_0^2}{2g \sin \alpha}$$

$$: \quad x_M = \frac{v_0^2}{2g \sin \alpha} \quad - 7$$

$$v_0 = \sqrt{2g x_M \sin \alpha}$$

$$v_0 = \sqrt{2 \times 9,81 \times 0,80 \times \sin 10}$$

$$v_0 = 1,65 \text{ m/s}$$